

# Mesh Simplification

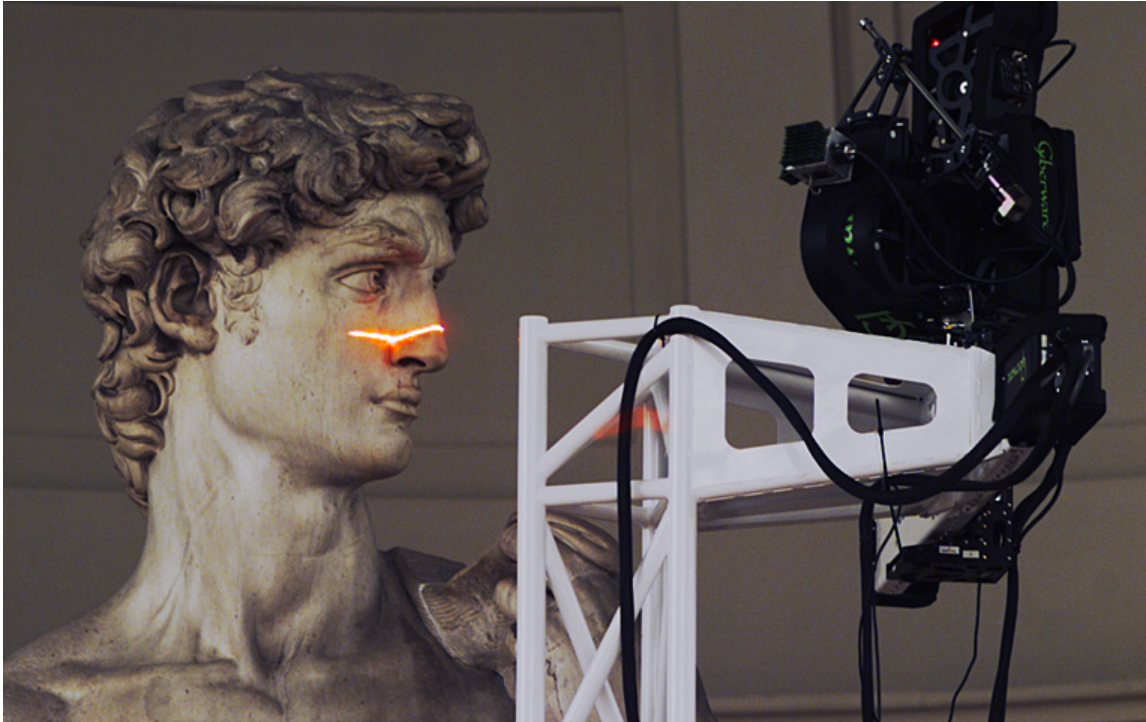
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CS418 Interactive Computer Graphics

John C. Hart

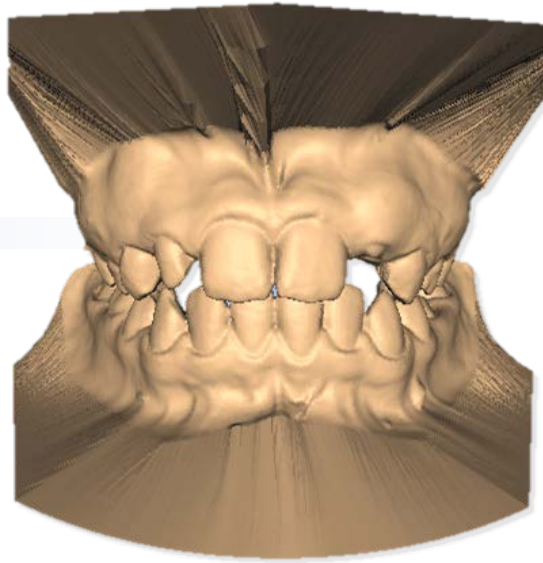
# Digital Michelangelo

- In 1998 Marc Levoy takes a sabbatical year in Florence to scan a bunch of Michelangelo sculptures
- David at 1mm resolution
- St. Matthew at 290 $\mu$ m resolution

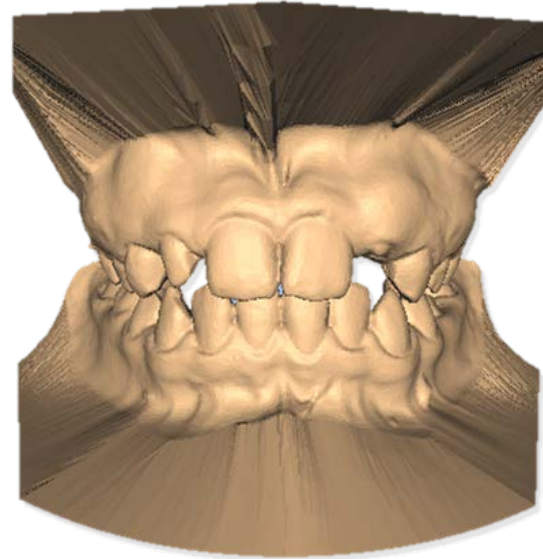


# Mesh Simplification

- Meshes often contain more triangles than are necessary for visual fidelity
  - Some surface generation methods run at a fixed resolution regardless of surface detail
  - Meshes might be used on different resolution devices, e.g. cellphone
- Need a method to reduce the number of triangles in a mesh
- Must figure out which triangles to remove while preserving visual shape and appearance



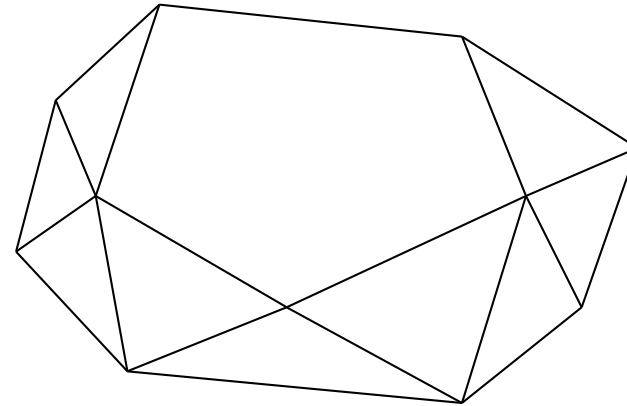
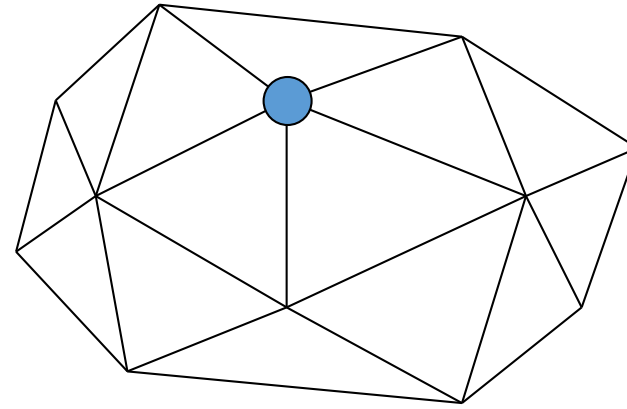
424,376 triangles



60,000 triangles

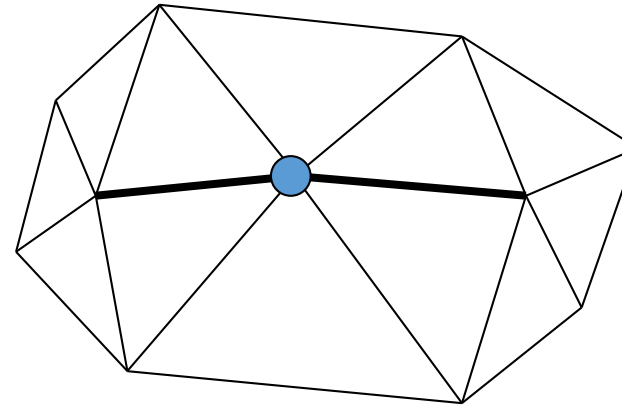
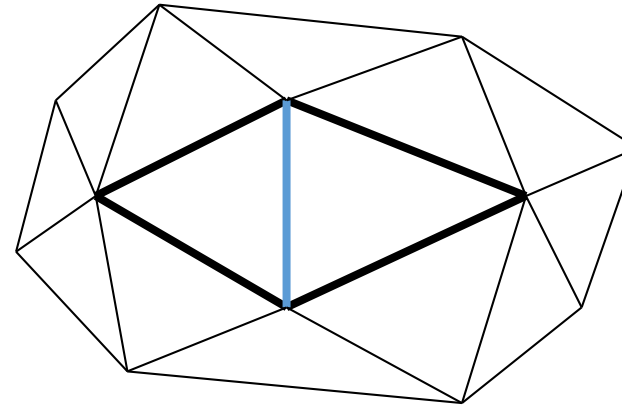
# Vertex Decimation

- Removing a vertex turns triangle mesh into polygon mesh



# Edge Collapse

- Removing a vertex turns triangle mesh into polygon mesh
- Removing an edge...
  - Merges two vertices into one
  - Removes two faces
  - Mesh still consists of triangles
- Which edges goes first?
- Where should the new vertices go?



# Vertex Importance

- Plane equation

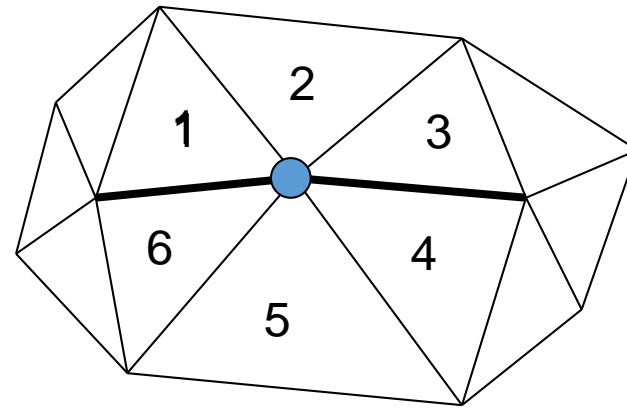
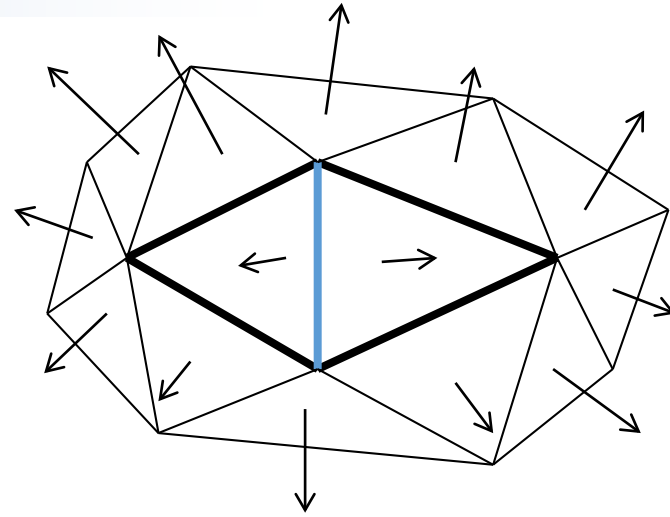
$$P_i(x,y,z) = A_ix + B_iy + C_iz + D$$

$$P_i(\mathbf{x}) = N_i \cdot \mathbf{x} + D$$

- $P_i(\mathbf{x})$  returns signed distance from  $\mathbf{x}$  to plane passing through polygon  $i$
- Best position of new vertex position minimizes squared distance to original planes of original polygons

$$QEM(\mathbf{v}) = \sum P_i(\mathbf{v})^2$$

(for adjacent polygons  $i$ )



# Matrix Representation

- Squared distance from point  $\mathbf{x}$  to plane  $P$

$$P^2(\mathbf{x}) = (Ax + By + Cz + D)^2$$

$$= [x \quad y \quad z \quad 1] \begin{bmatrix} A^2 & AB & AC & AD \\ AB & B^2 & BC & BD \\ AC & BC & C^2 & CD \\ AD & BD & CD & D^2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

$$= \mathbf{x}^T Q \mathbf{x}$$

- Sum of squared distances from point  $\mathbf{x}$  to planes  $P_1$  and  $P_2$

$$P_1^2(\mathbf{x}) + P_2^2(\mathbf{x}) = \mathbf{x}^T Q_1 \mathbf{x} + \mathbf{x}^T Q_2 \mathbf{x} = \mathbf{x}^T (Q_1 + Q_2) \mathbf{x}$$



# Quadric Error Metric

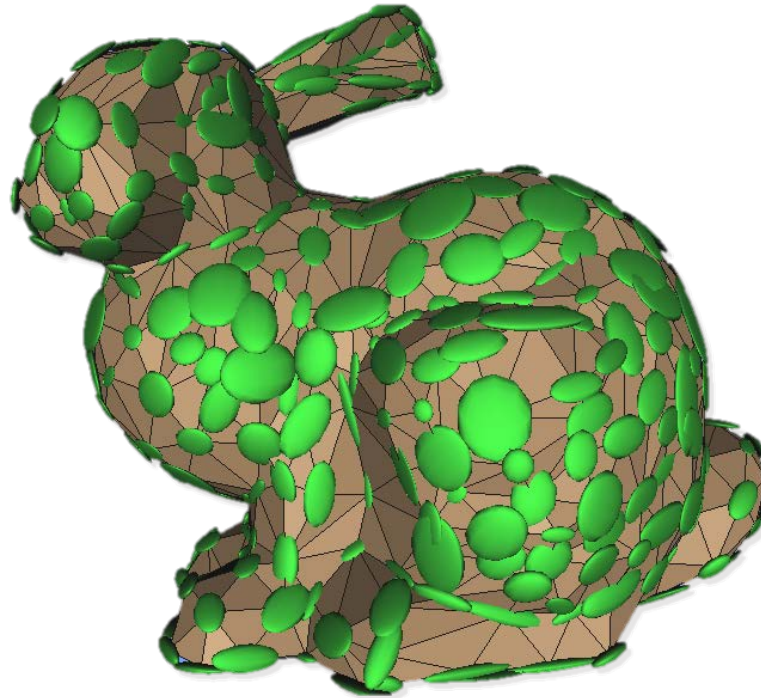
- Find  $Q$  for each vertex  $\mathbf{v}$

$$Q(\mathbf{v}) = \sum Q_i$$

(for adjacent polygons  $i$ )

- Edge collapse edges whose vertices  $\mathbf{v}_1, \mathbf{v}_2$  have least  $Q(\mathbf{v}_1) + Q(\mathbf{v}_2)$
- New vertex  $\mathbf{v}_{12}$  can be at  $\mathbf{v}_1$  or  $\mathbf{v}_2$  or optimally at ...

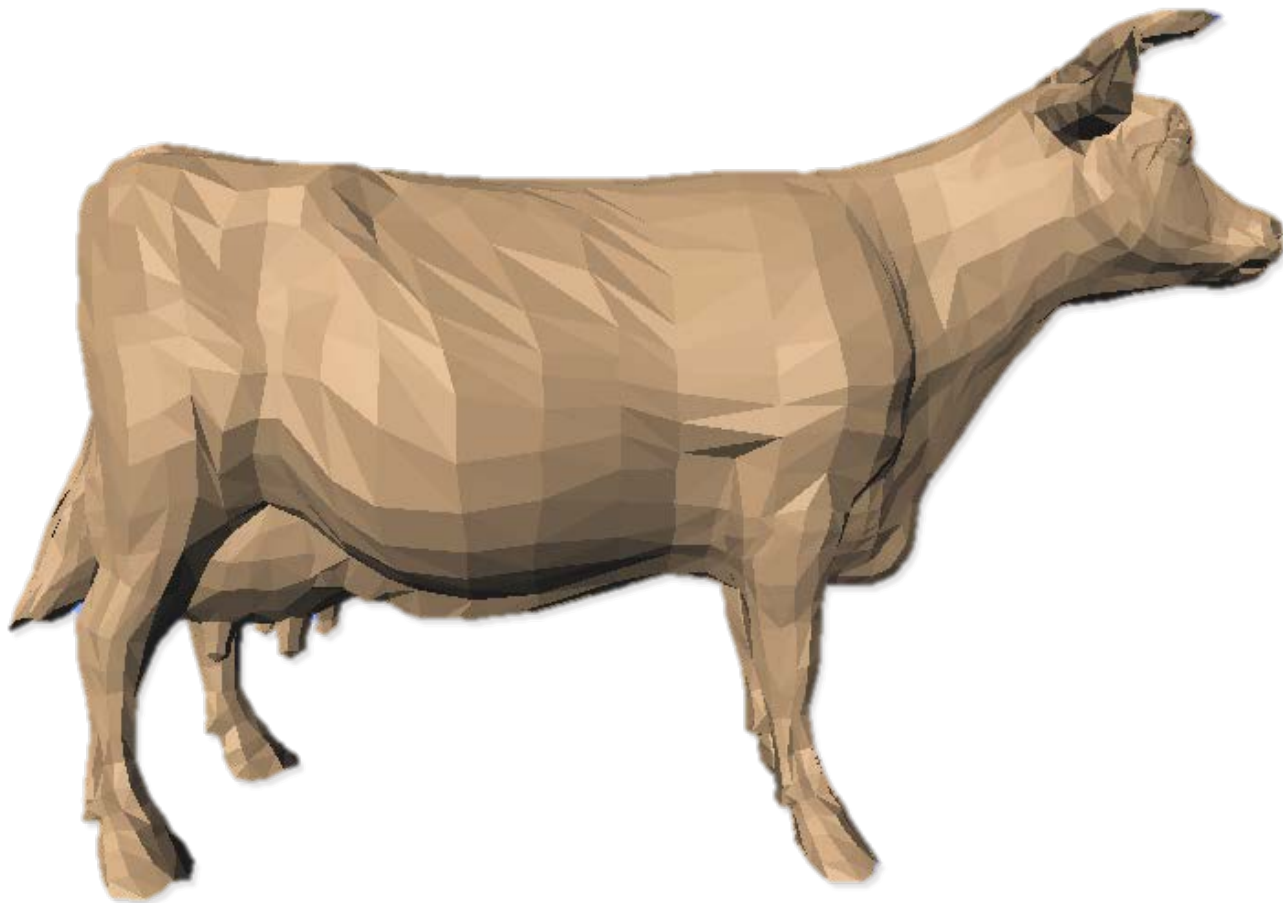
$$\mathbf{v}_{12} = - \begin{bmatrix} A^2 & AB & AC \\ AB & B^2 & BC \\ AC & BC & C^2 \end{bmatrix}^{-1} \begin{bmatrix} AD \\ BD \\ CD \end{bmatrix}$$





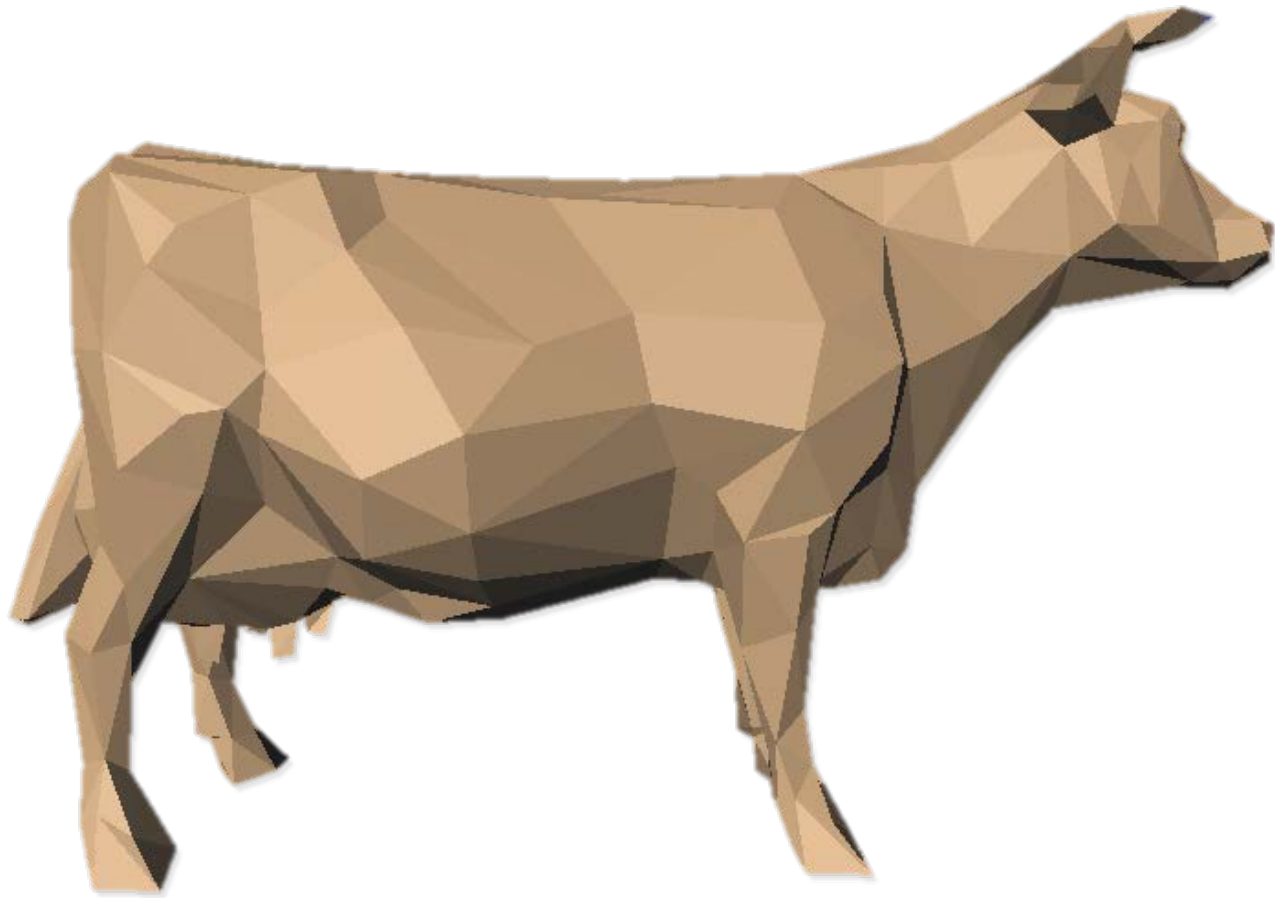
# Examples

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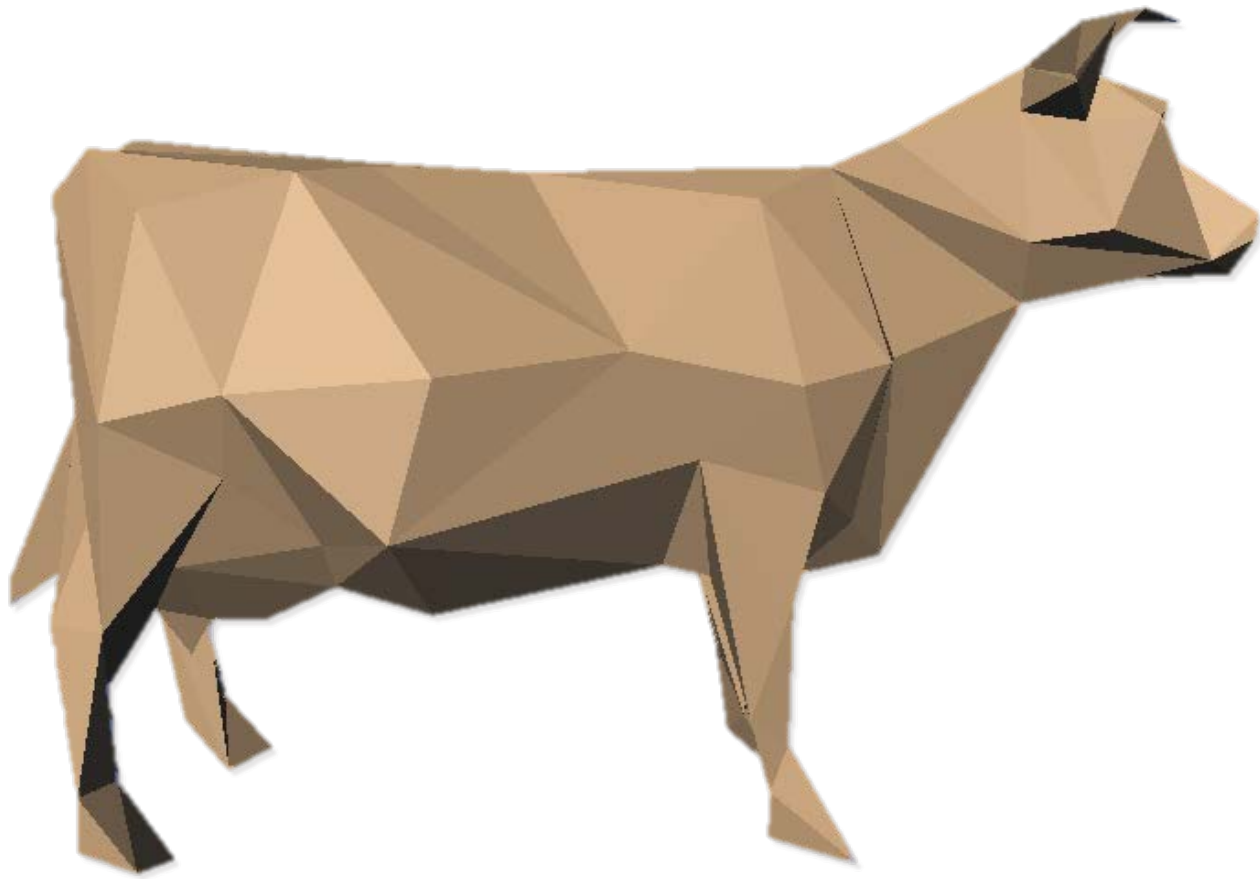
# Examples

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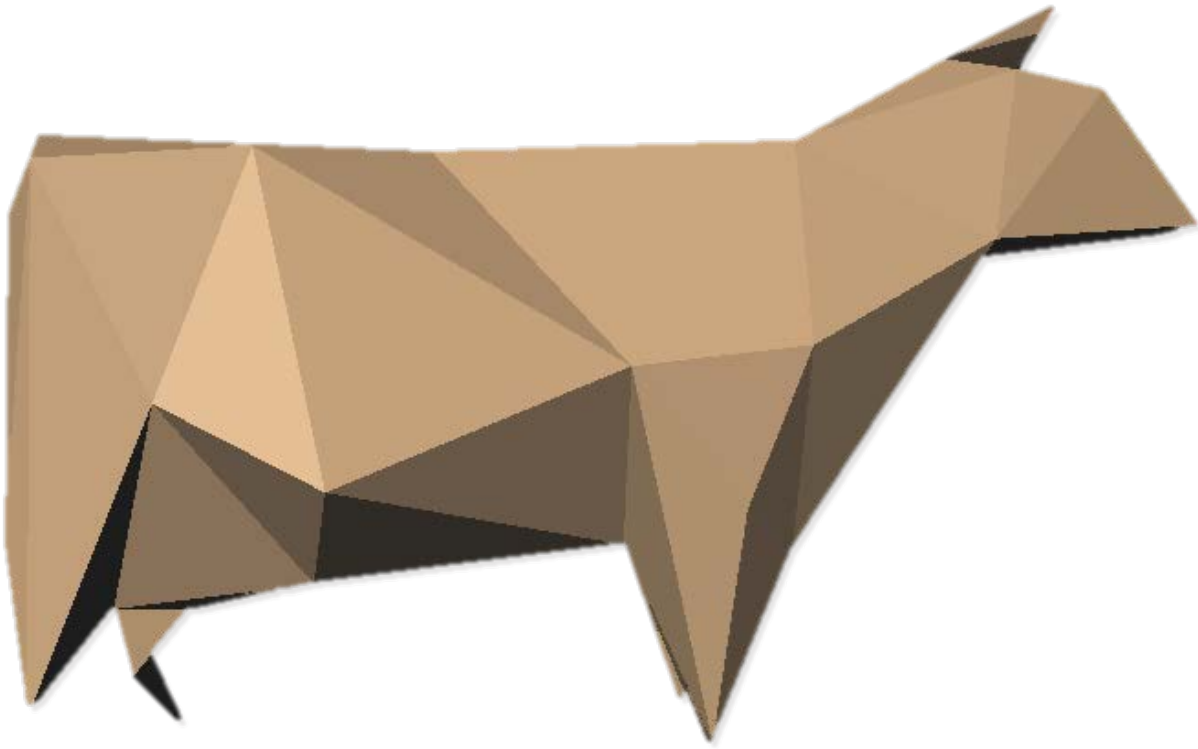
# Examples

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# Examples

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# Examples

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